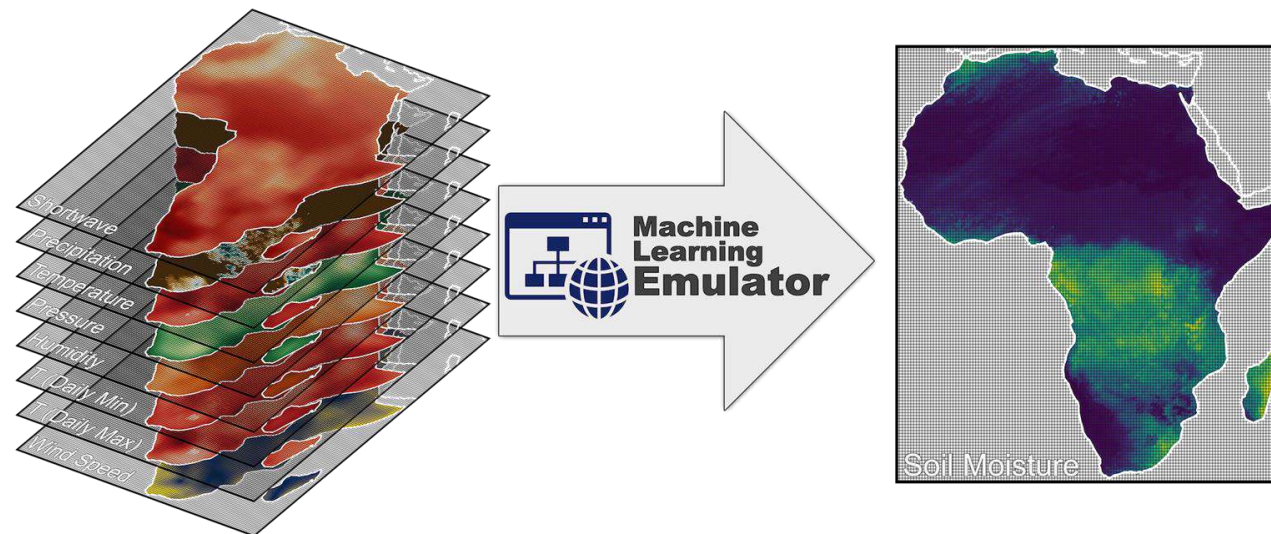


A Machine Learning emulator of JULES soil moisture: Applications to African drought

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National Centre for Earth Observation
University of Leicester

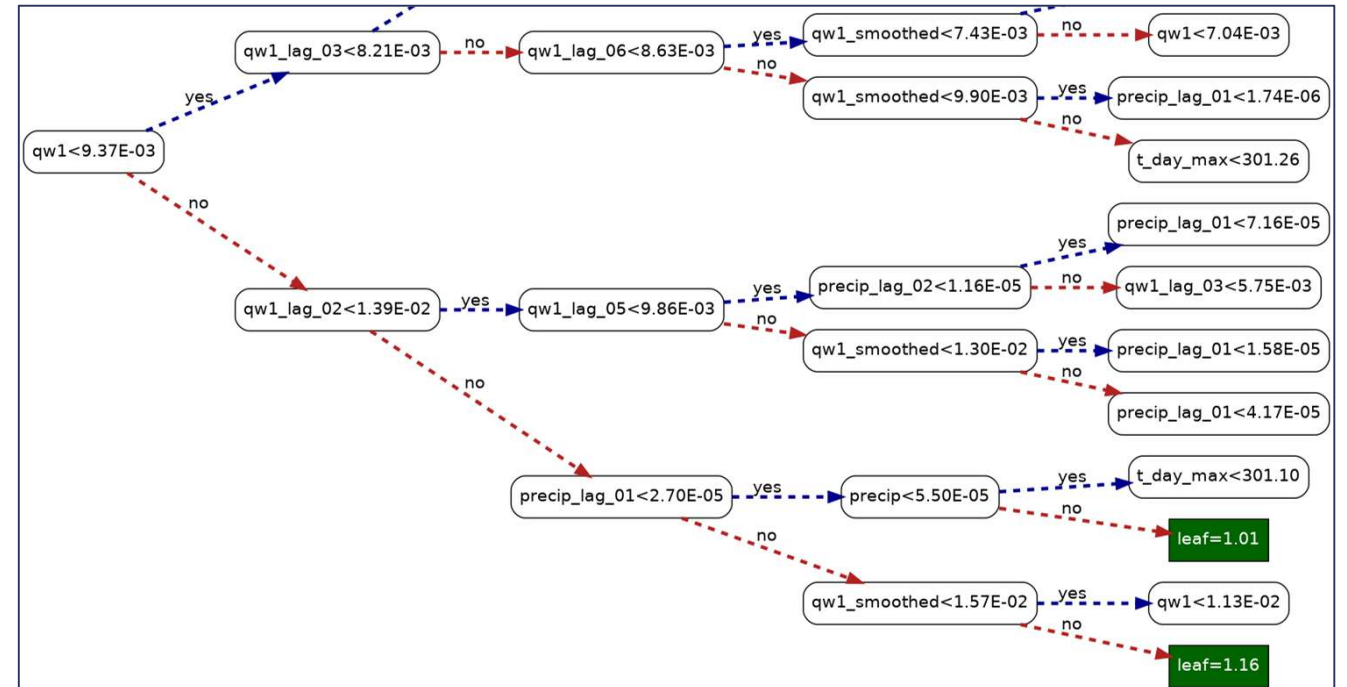
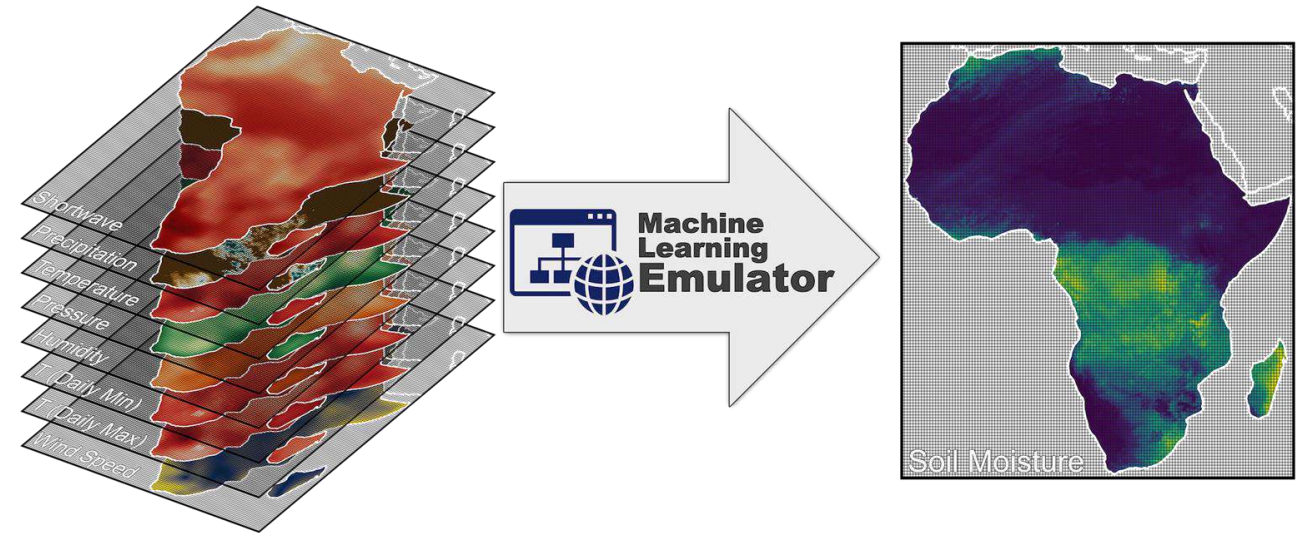
Machine Learning Emulation

- ❑ **Key Question:** Can we emulate JULES soil moisture with a simple/fast machine-learning based algorithm?
- ❑ **Requirements and Objectives:**
 - ❑ Successfully develop emulator for African soil moisture
 - ❑ Needs to be fast and light-weight
 - ❑ Capable of running in a Jupyter Notebook and/or in the cloud
 - ❑ Assess emulator performance vs JULES simulations
 - ❑ Apply emulator to ISIMIP-driven climate scenarios to allow exploration of climate responses



Machine Learning Emulation

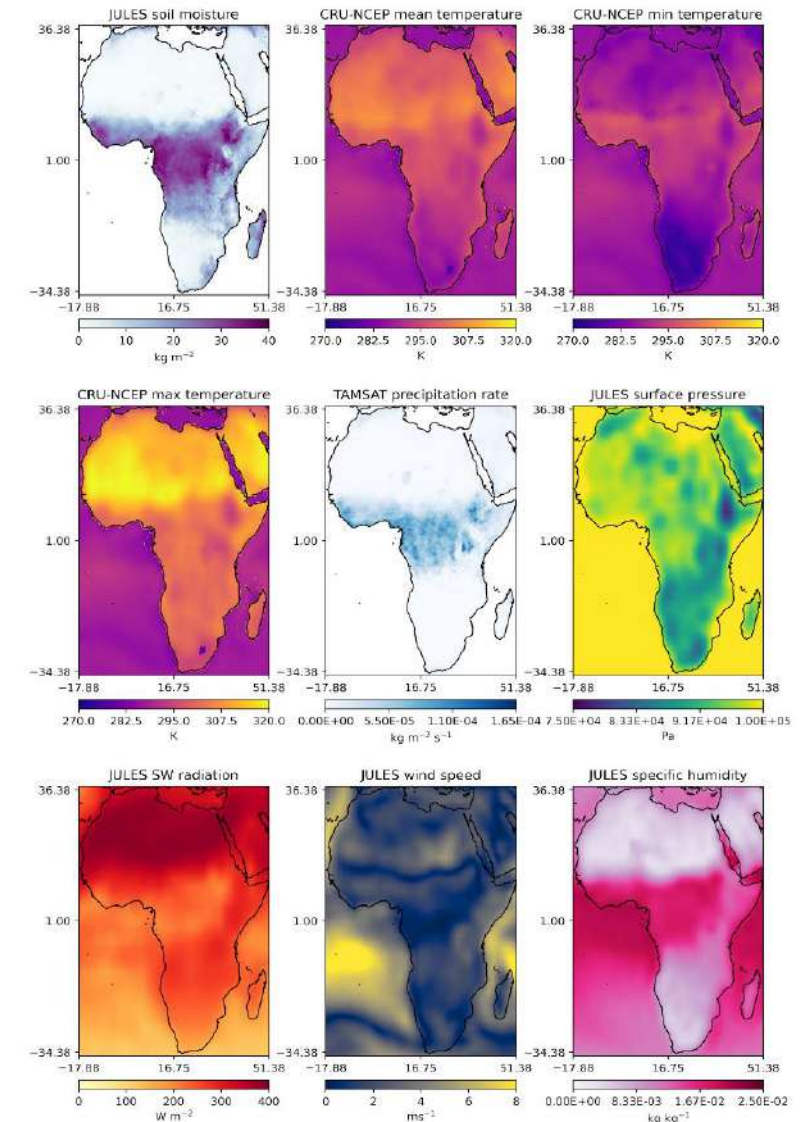
- ❑ We tested a **range** of machine learning methods:
 - ❑ Support Vector Machines, Penalised Regression, Decision Tree Methods
 - ❑ **All** worked (surprisingly) well but XGBoost has best performance
- ❑ The **Extreme Gradient Boosting** (XGBoost) algorithm
 - ❑ Output value of a single tree is determined through succession of **specific value tests** applied to input variables.
 - ❑ Gradient descent is used to determine which set of possible trees would **minimise the prediction error**
 - ❑ Nonlinear functions can be represented as a large **ensemble of trees** to cover a range of different scenarios.



Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

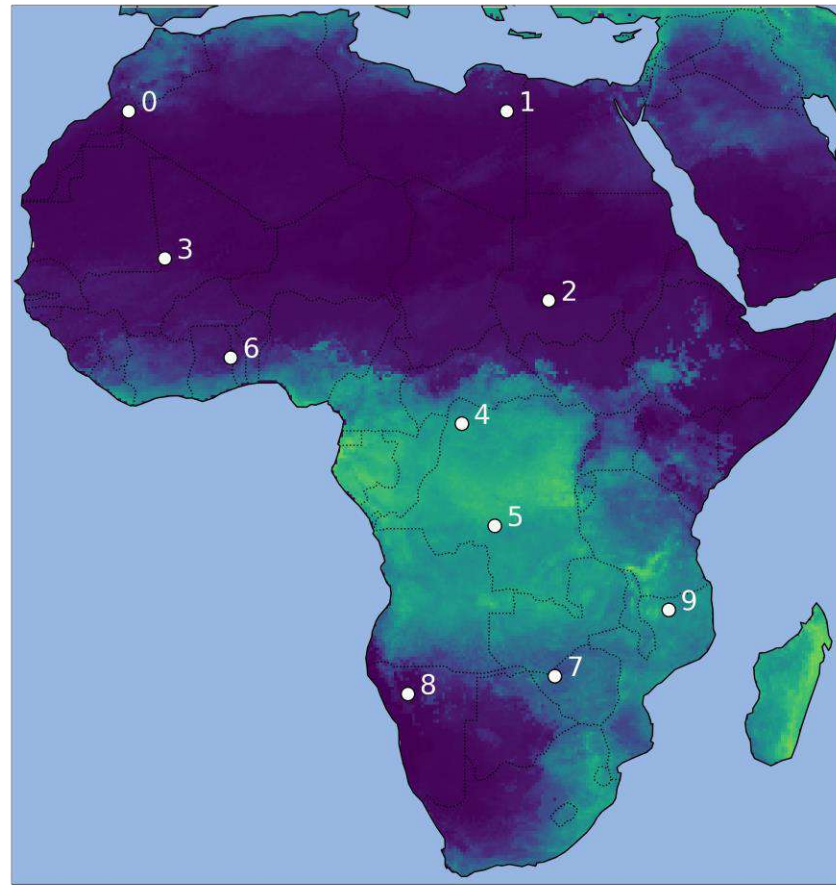
Training data selection

- ❑ To train and test the emulator, JULES simulations of African soil moisture were made between **1999-2020** using **TAMSAT (precipitation)** and **CRU-NCEP (temperature)** as input data
- ❑ **2000-2019** used as **training** data, while **2020** reserved for **validation** only
- ❑ Initially, **26 variables** were used as training data, taken from the following daily mean variables from the JULES output:
 - ❑ Temperature (also daily minimum & maximum)
 - ❑ Downward shortwave solar radiation
 - ❑ Precipitation
 - ❑ Specific humidity
 - ❑ Surface pressure
 - ❑ Wind speed
- ❑ To introduce memory of soil moisture dependence on seasonality and prior weather conditions, we also included:
 - ❑ 20-day smoothed temperature, specific humidity, and precipitation
 - ❑ 1-7 day lagged specific humidity and precipitation

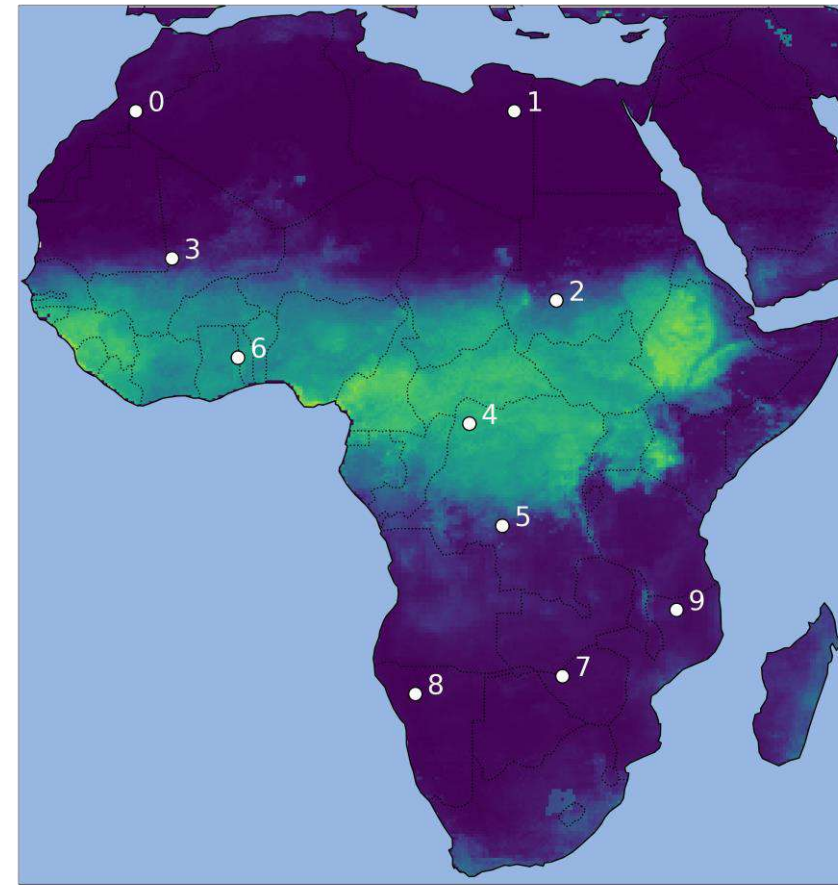


Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

Training data needs to be representative of all possible African climates – sample data from 10 grid cells



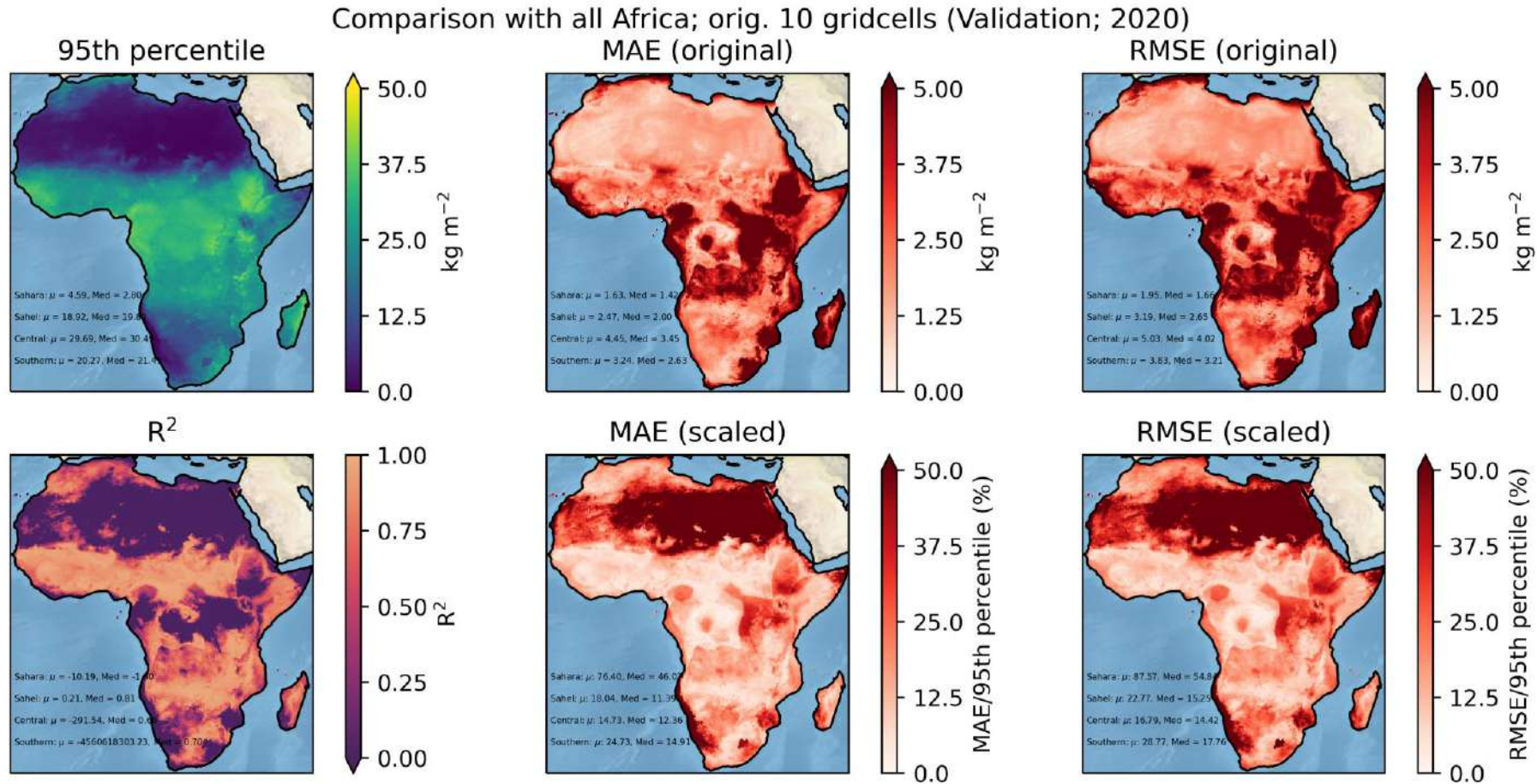
JULES Soil Moisture [kg/m²] for 2019-03-01



JULES Soil Moisture [kg/m²] for 2019-08-01

Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

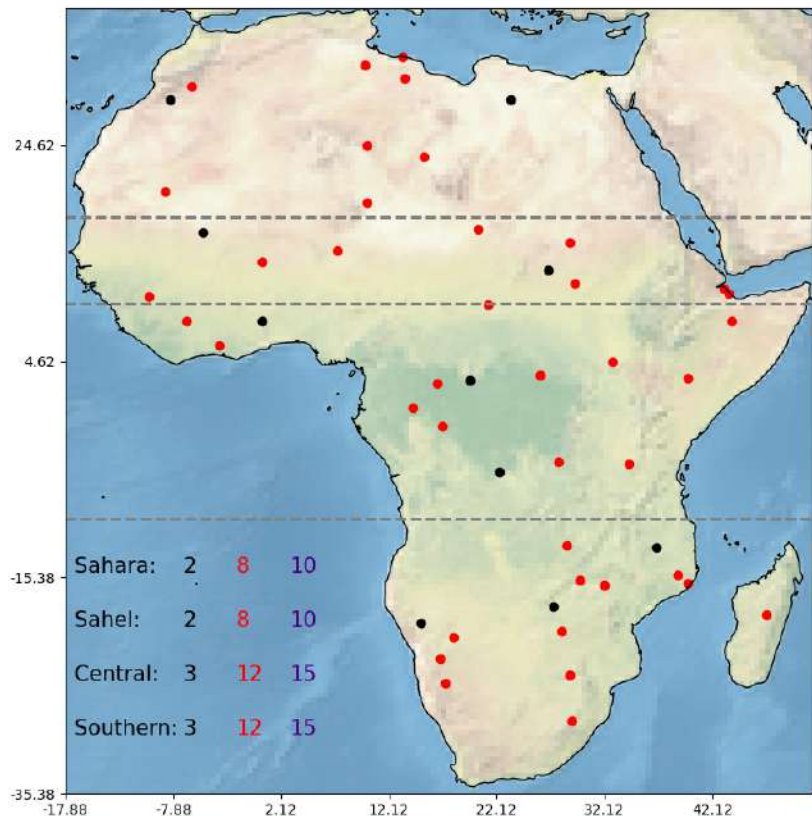
*Initial results trained with **only 10 grid points** demonstrated good overall agreement, but **poor performance** over the Sahara and Southern Africa*



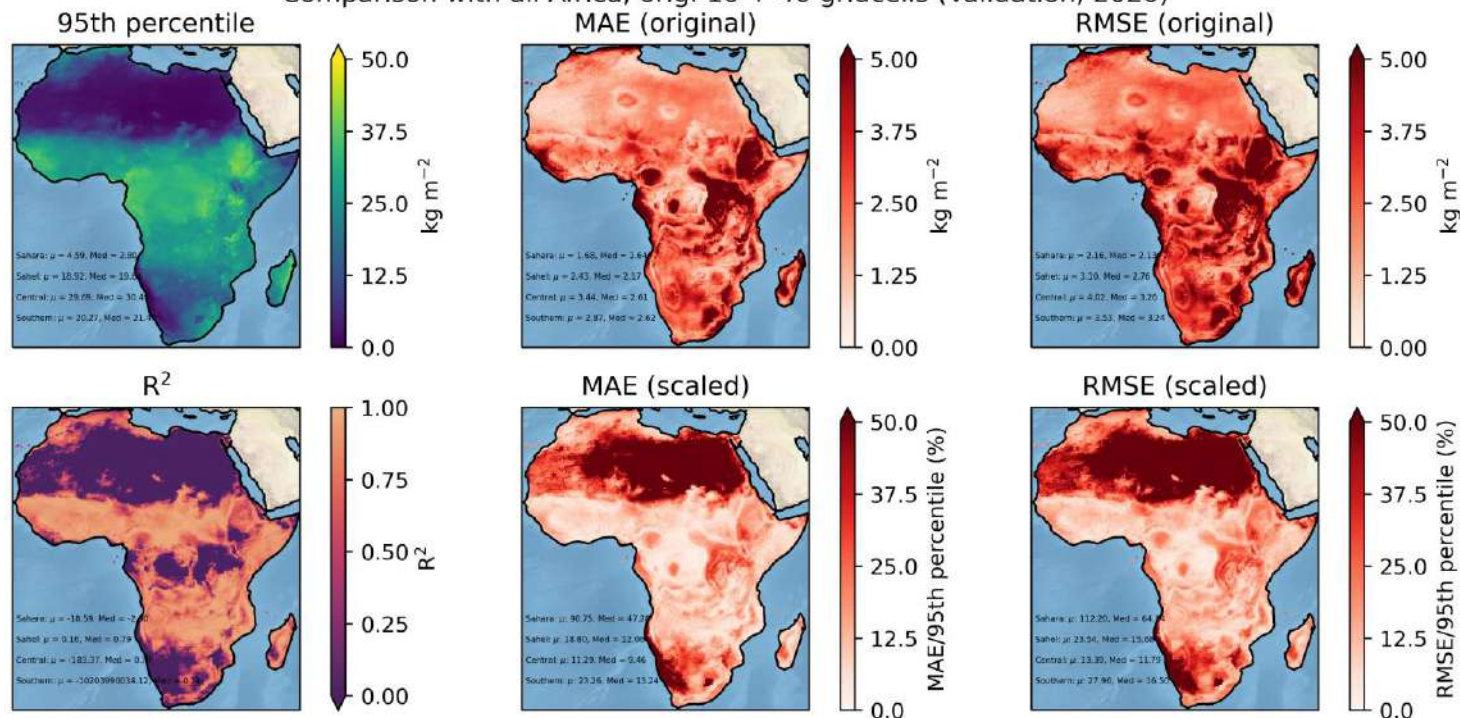
Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

Adding more grid cells to training dataset helps to improve emulator performance...

Tested 10, 50, 200 and 1000 grid cells in training dataset



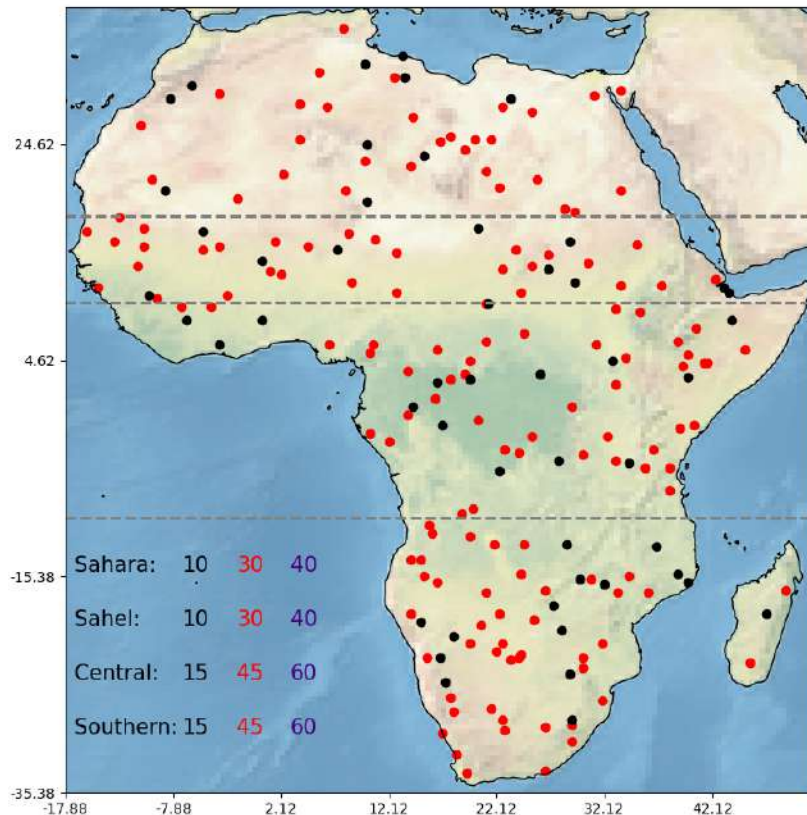
Comparison with all Africa; orig. 10 + 40 gridcells (Validation; 2020)



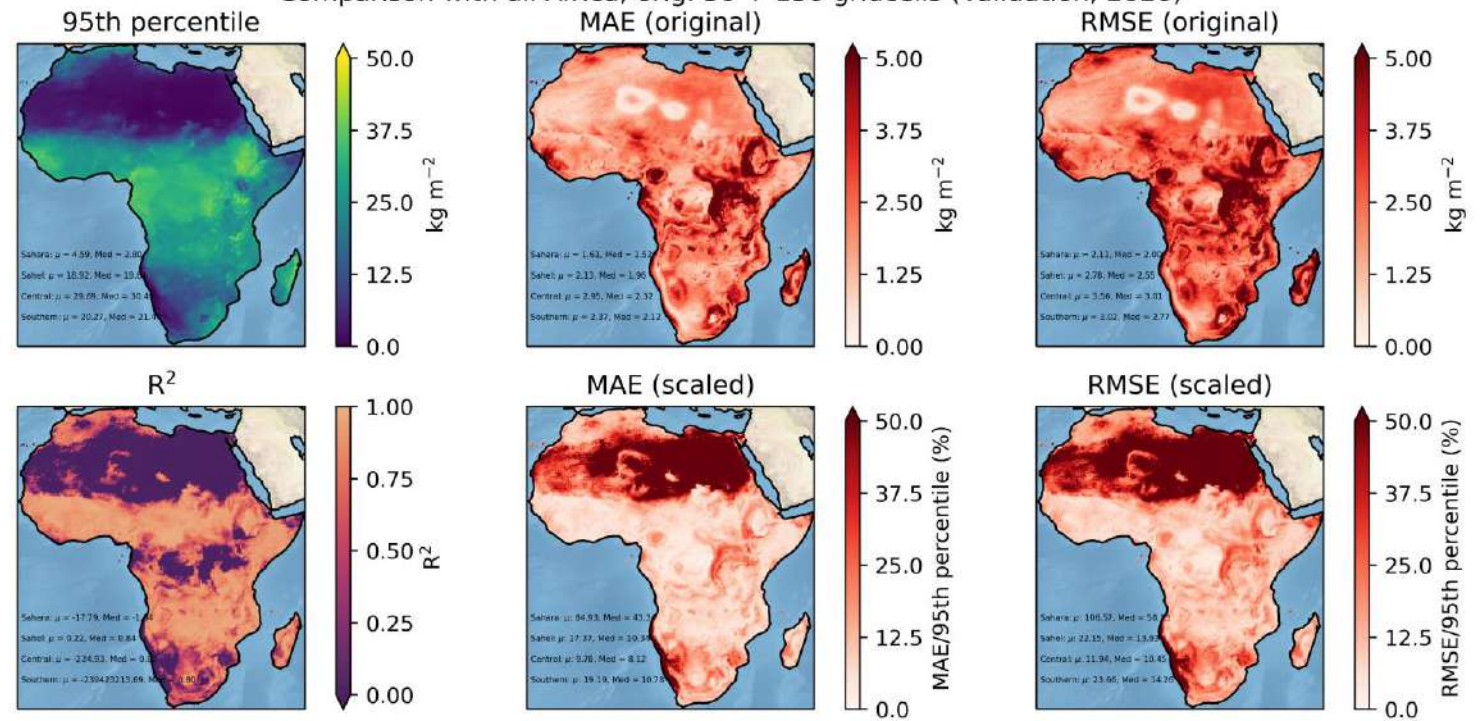
50 training grid cells

Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

Adding more grid cells helps to improve emulator performance... to an extent



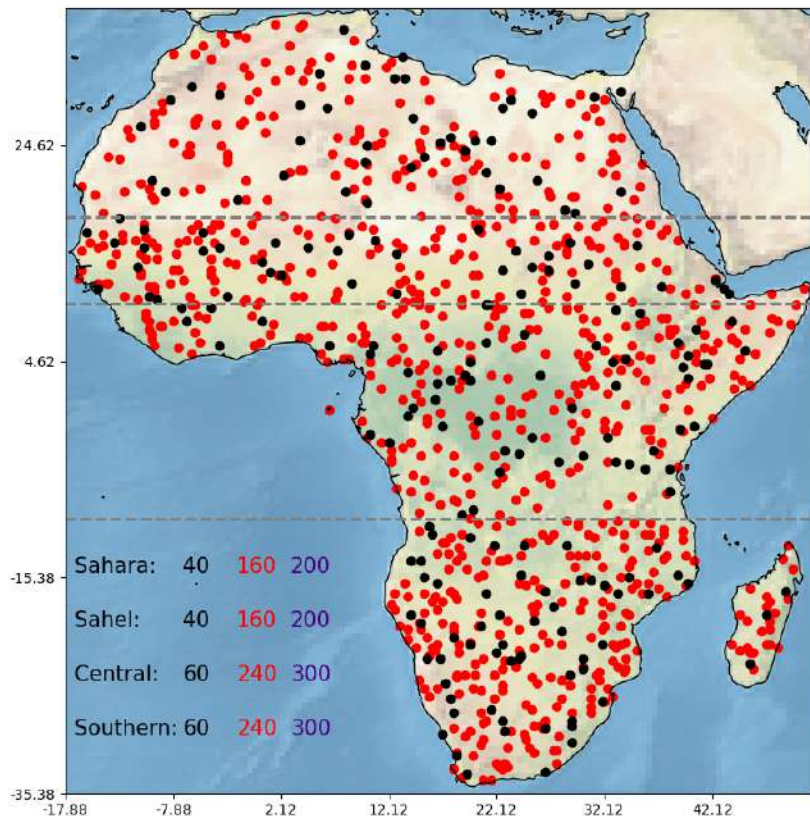
Comparison with all Africa; orig. 50 + 150 gridcells (Validation; 2020)



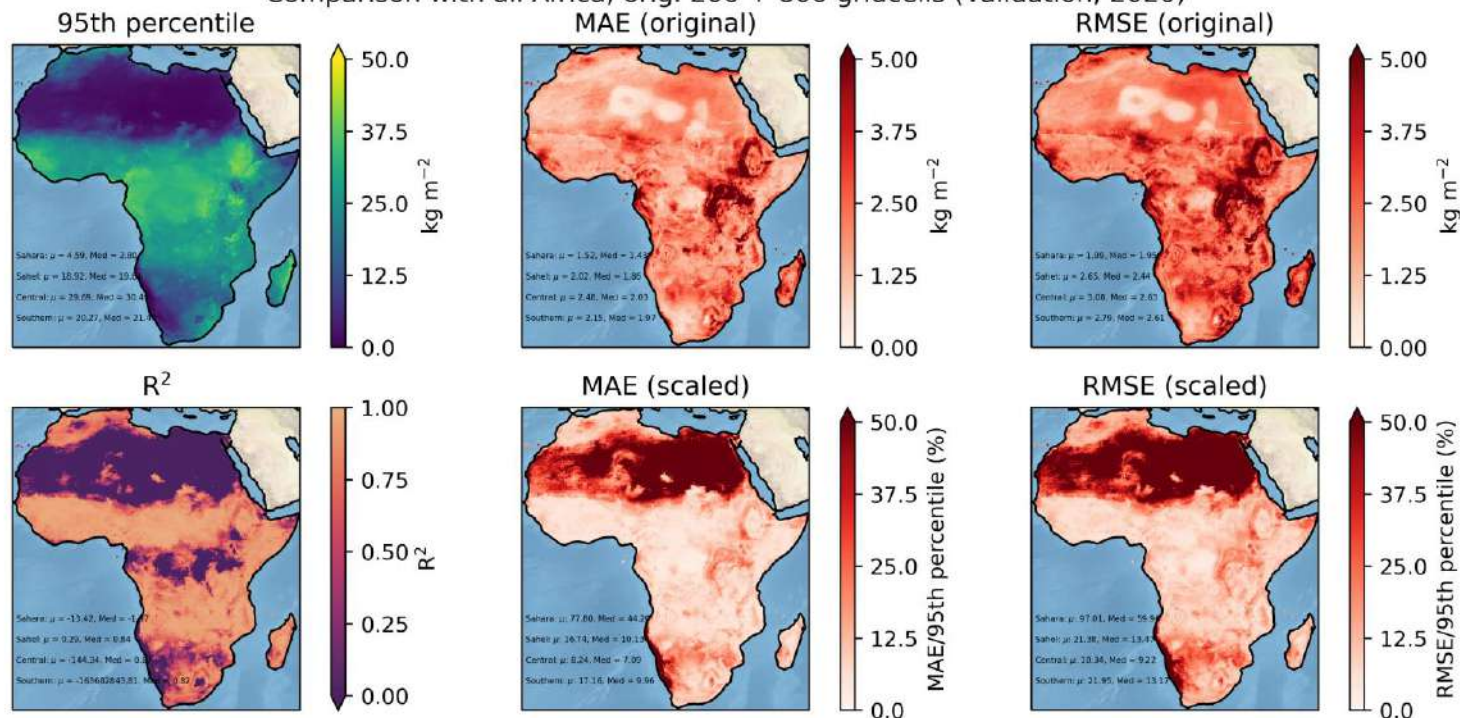
200 training grid cells

Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

Adding more grid cells helps to improve model performance... to an extent



Comparison with all Africa; orig. 200 + 800 gridcells (Validation; 2020)

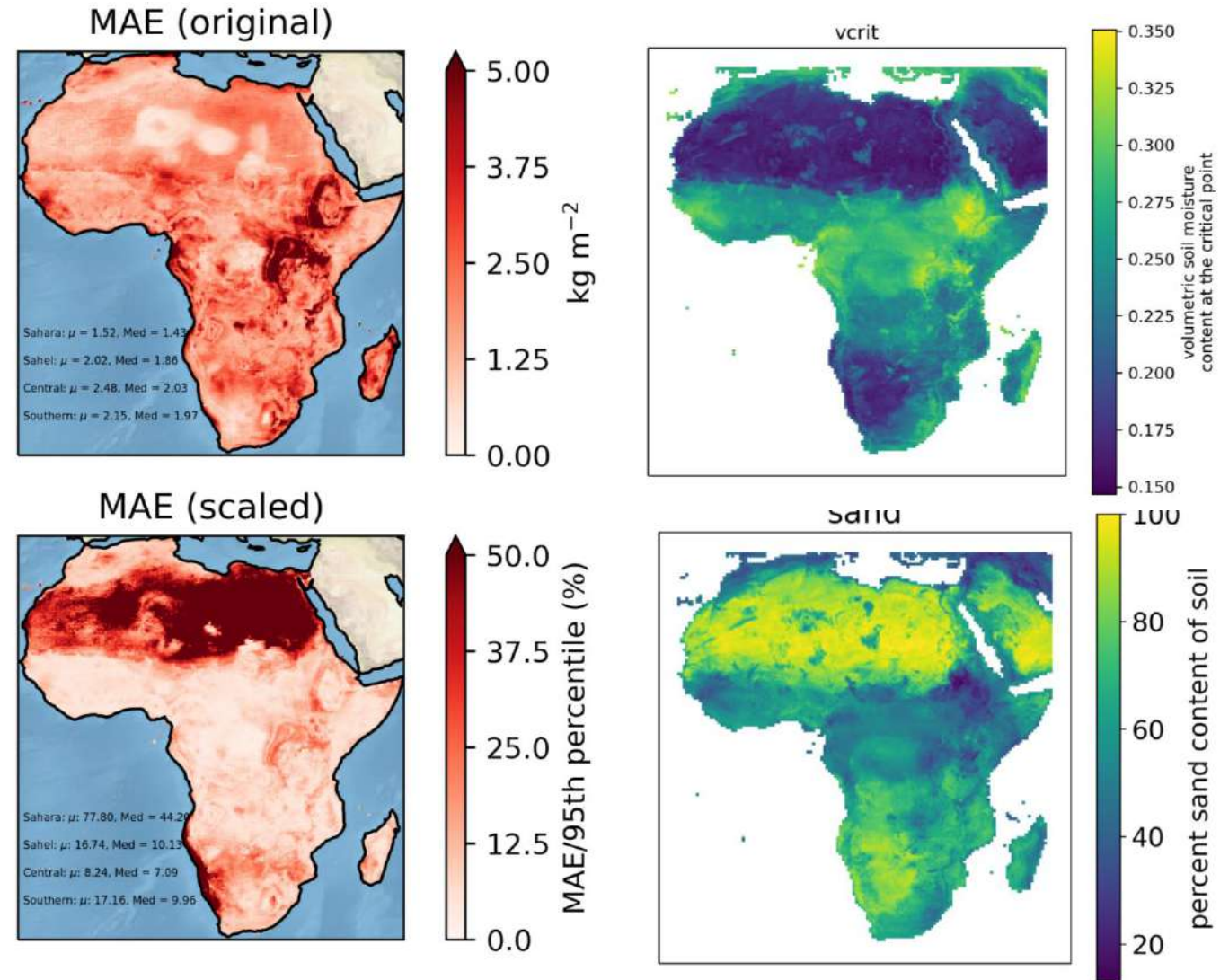


1000 training grid cells

Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

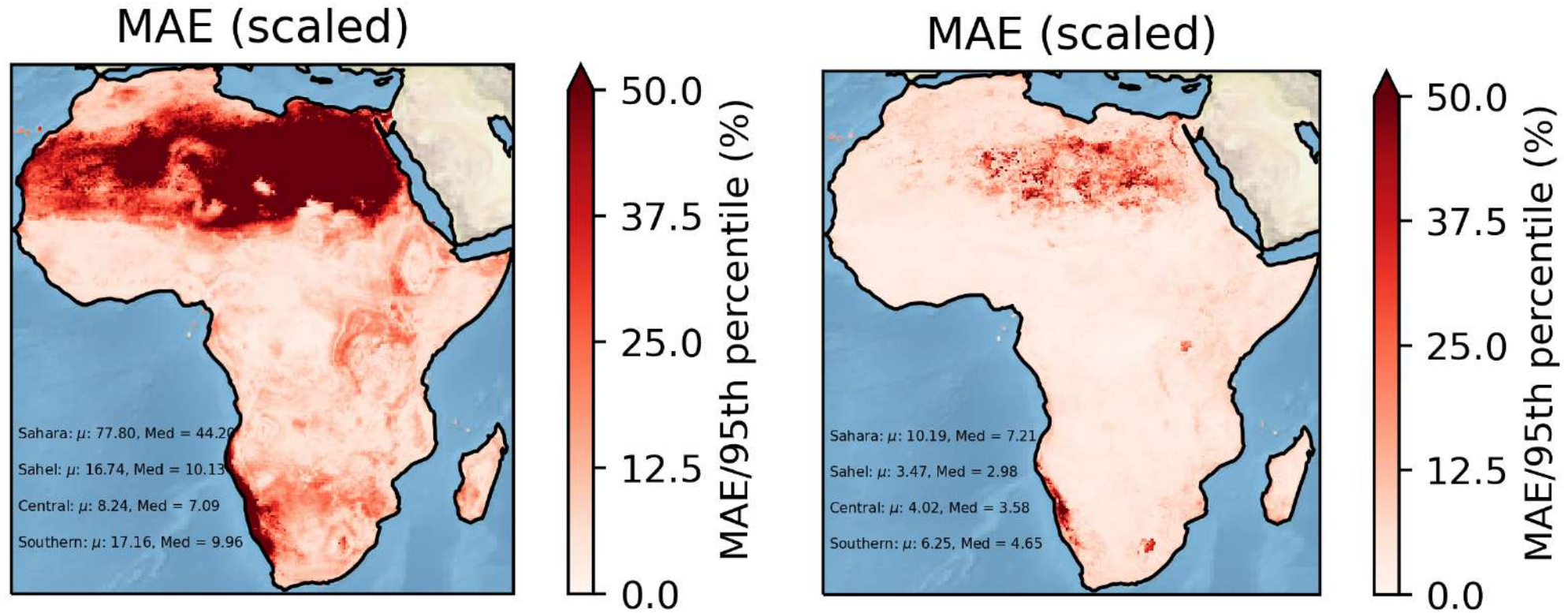
Update training dataset with ancillary information

- ❑ Despite improved accuracy, the overall model performance is still hampered by poor agreement over the Sahara and Namibian deserts, and savannah in Southern Africa – **Does the emulator need contextual information too?**
- ❑ Our biases have **similar patterns** to some of the ancillary data...
- ❑ Solution: Update training dataset with time-invariant JULES **ancillary variables** for each grid cell:
 - ❑ Soil type coverage
 - ❑ Soil bulk density
 - ❑ Vegetation type coverage
 - ❑ Soil carbon storage
 - ❑ Topography
 - ❑ Soil hydrological information



Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

Adding ancillary information to training dataset greatly improves emulator performance

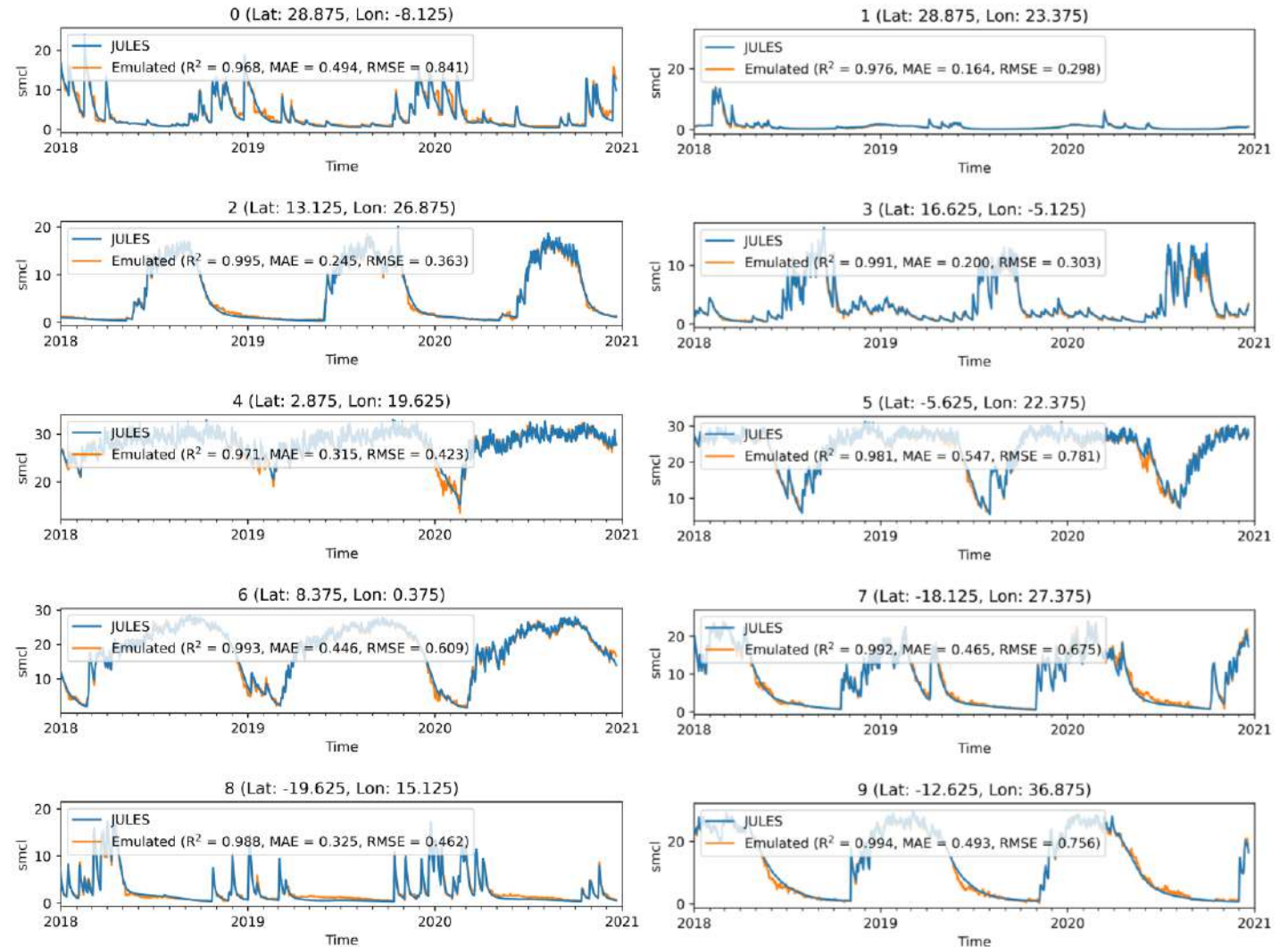
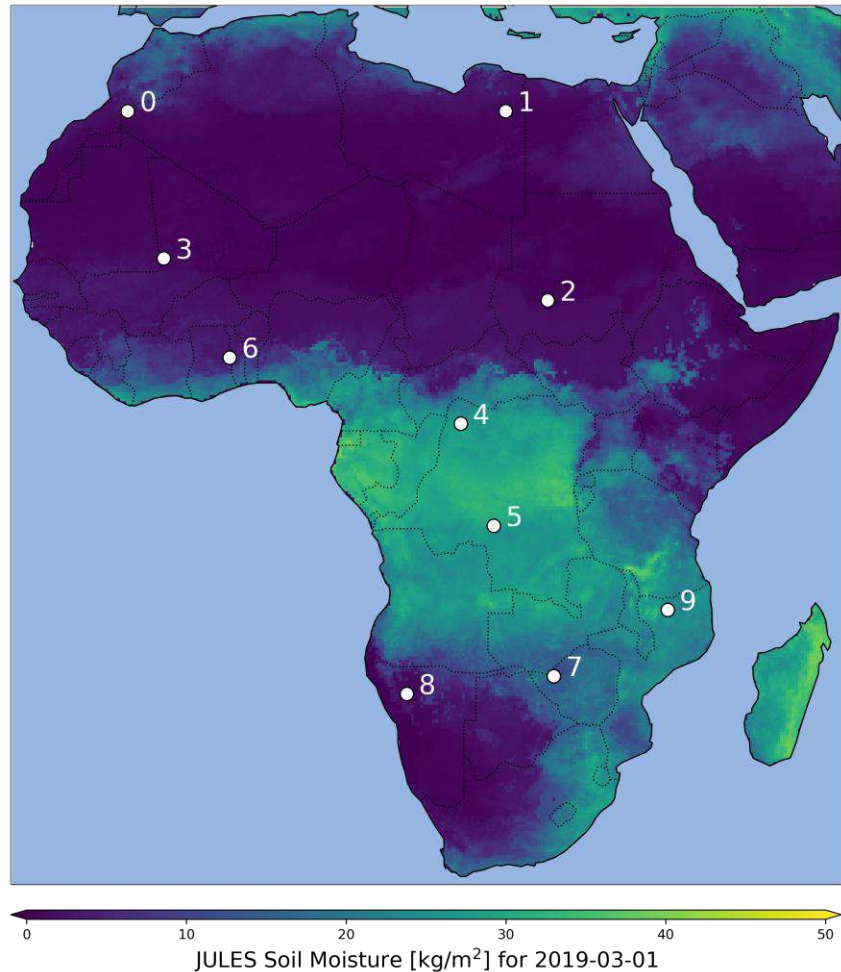


No ancillary data

With ancillary data

Emulating JULES simulations driven by TAMSAT/CRU-NCEP data

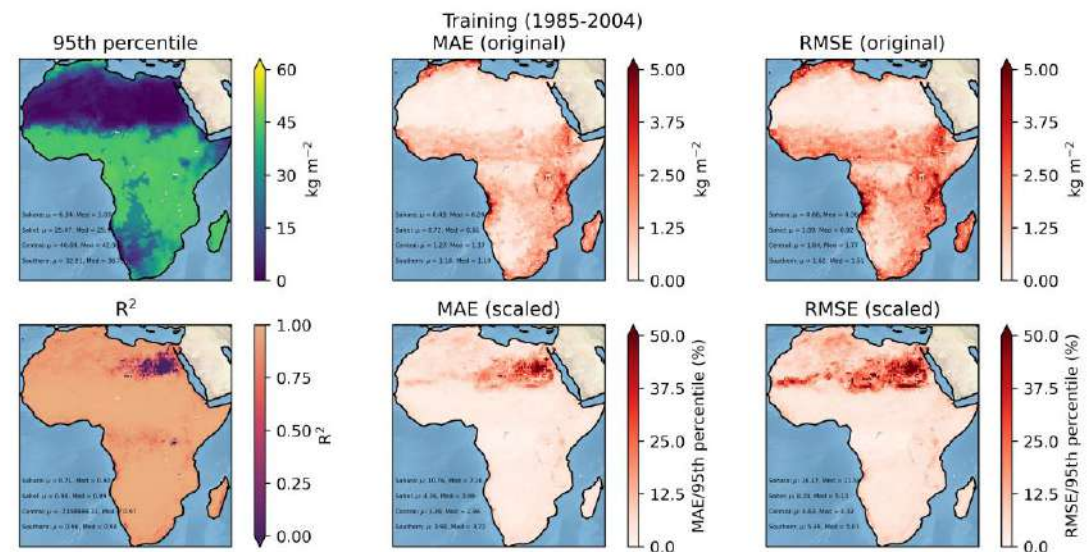
The emulator also shows excellent temporal agreement with the original JULES soil moisture



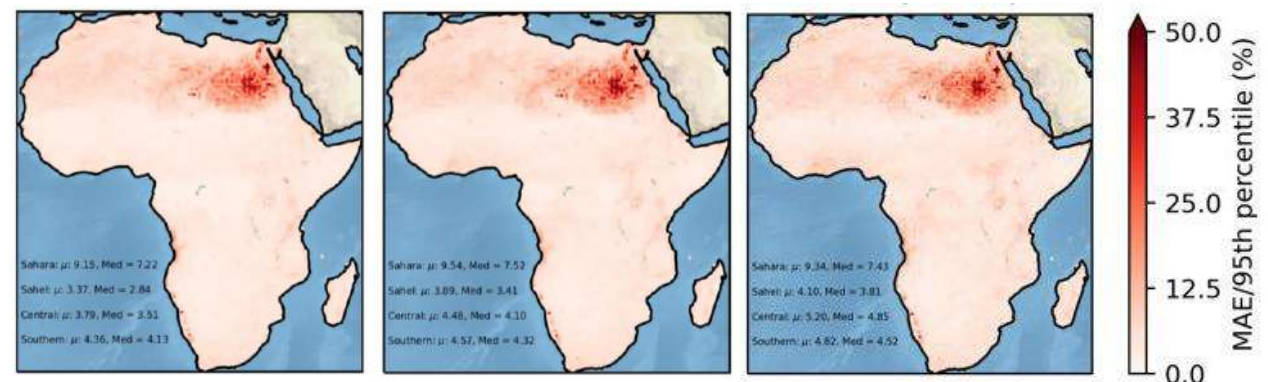
Emulating JULES forecasts using ISIMIP climate scenario data

Emulator retrained using ISIMIP historical data (1985-2005), then applied to predict RCP scenarios from 2006-20099

- JULES ISIMIP setup different than historical setup (resolution, ancils, etc) so model retrained, including $[CO_2]$ as a feature
- Emulator used to predict soil moisture for ISIMIP-based RCP **climate scenarios**: RCP2.6 (< 2°C rise), RCP6.0 and RCP8.5 (BAU)
- For all of Africa, the **error is typically < a few %** after training on 1000 locations (~2% of total grid cells)
- Emulator reproduces 2006–20099 period simulated by JULES **very well**

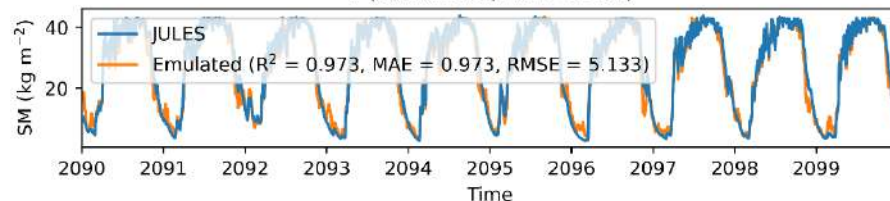


MAE from emulating ISIMIP simulations



HADGEM2-ES, RCP2.6, 2090-2099

6 (Lat: 8.250, Lon: 0.250)



RCP 2.6

RCP 6.0

RCP 8.5

Summary and Conclusions

- ❑ **Successfully** developed machine-learning based emulator for JULES soil moisture
- ❑ Initial testing of various methods **all** gave good results but settled on XGBoost algorithm
- ❑ Emulator is **VERY** fast/light-weight (runs in a few ms per grid cell per year)
- ❑ Performance metrics (MAE and RMSE) used to assess performance over whole of Africa
- ❑ Emulator performance improved iteratively by:
 - ❑ Adding in more training **locations** (better sampling of feature-space)
 - ❑ Adding in more training **features** (e.g. soil ancil data)
- ❑ Final model performs **extremely well**
 - ❑ Error **typically < a few %** compared to original JULES simulation
- ❑ Model retrained on JULES ISIMIP historical simulations
 - ❑ Required as ISIMIP suite has different settings (different ancils, different resolution, etc)
 - ❑ Performance of ISIMIP simulations **very good** across multiple RCPs
 - ❑ Emulator can be used to **quickly explore** JULES response to different climate scenarios
- ❑ Lots of potential for expanding
 - ❑ Extend to other JULES processes
 - ❑ Rob/Tristan have proposal under consideration to do this for GPP
 - ❑ Extend to other land surface models and cross-compare
 - ❑ Do some interesting science with it!