

Machine-Learning Emulators of Land Surface Model 'JULES' as Digital Twin building blocks

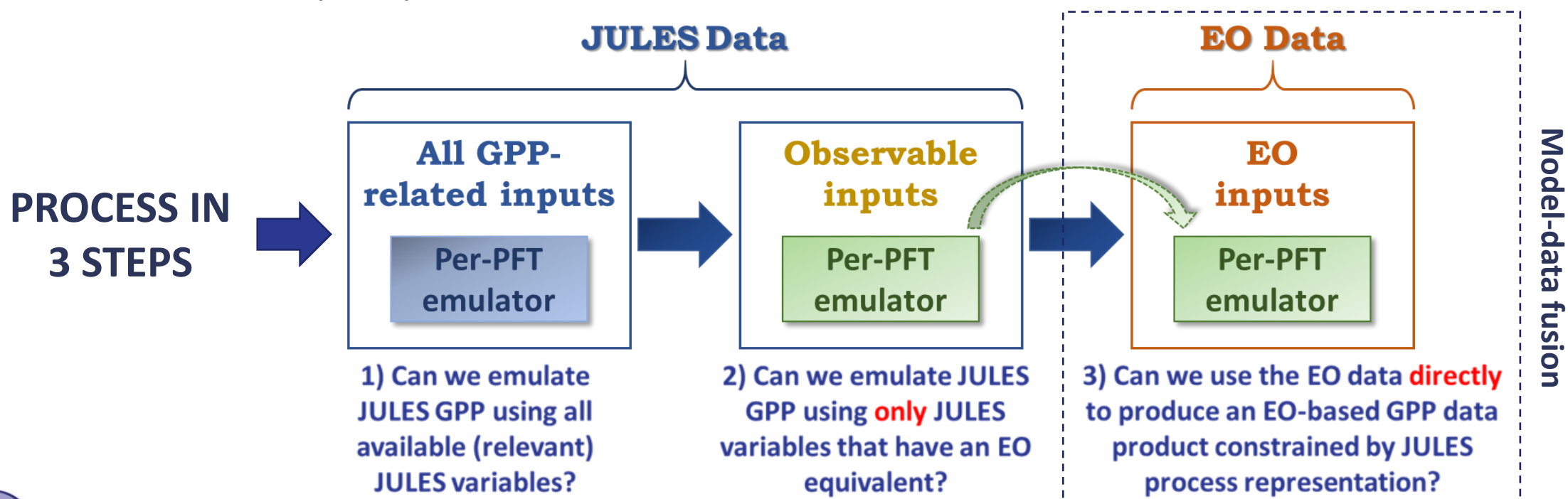
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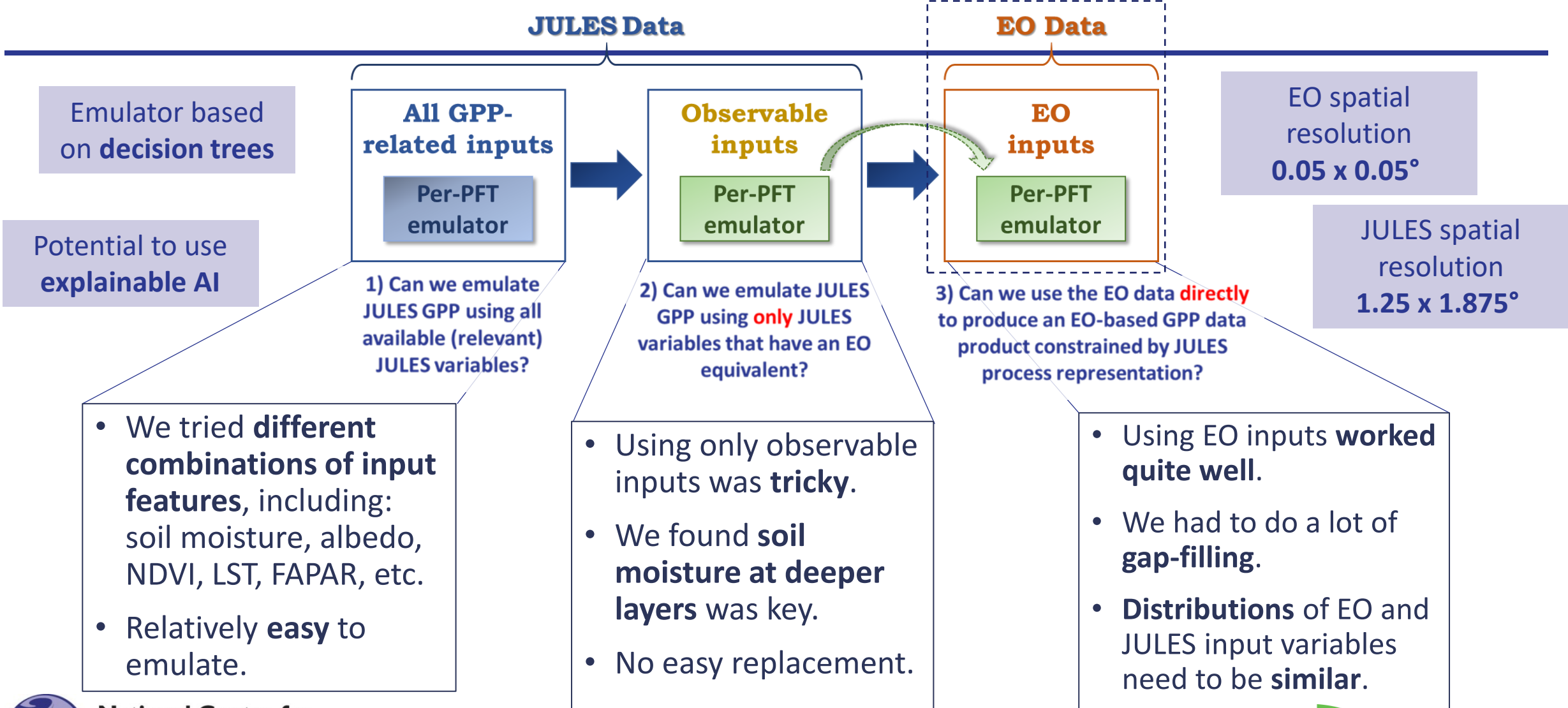


Emulating Europe's Carbon Cycle

- The **carbon cycle** over Europe is still **highly uncertain** and neither observations nor models alone are capable of addressing these issues.
- Emulators allow greater **understanding** of the model behaviour and let us explore the different relationships between the drivers and carbon fluxes.
- We can then use **emulator with Earth Observation data** to derive **new** datasets that are explicitly tied to observations and can make use of their uncertainties.



Emulating JULES GPP



Results: Emulating JULES – maps of statistics

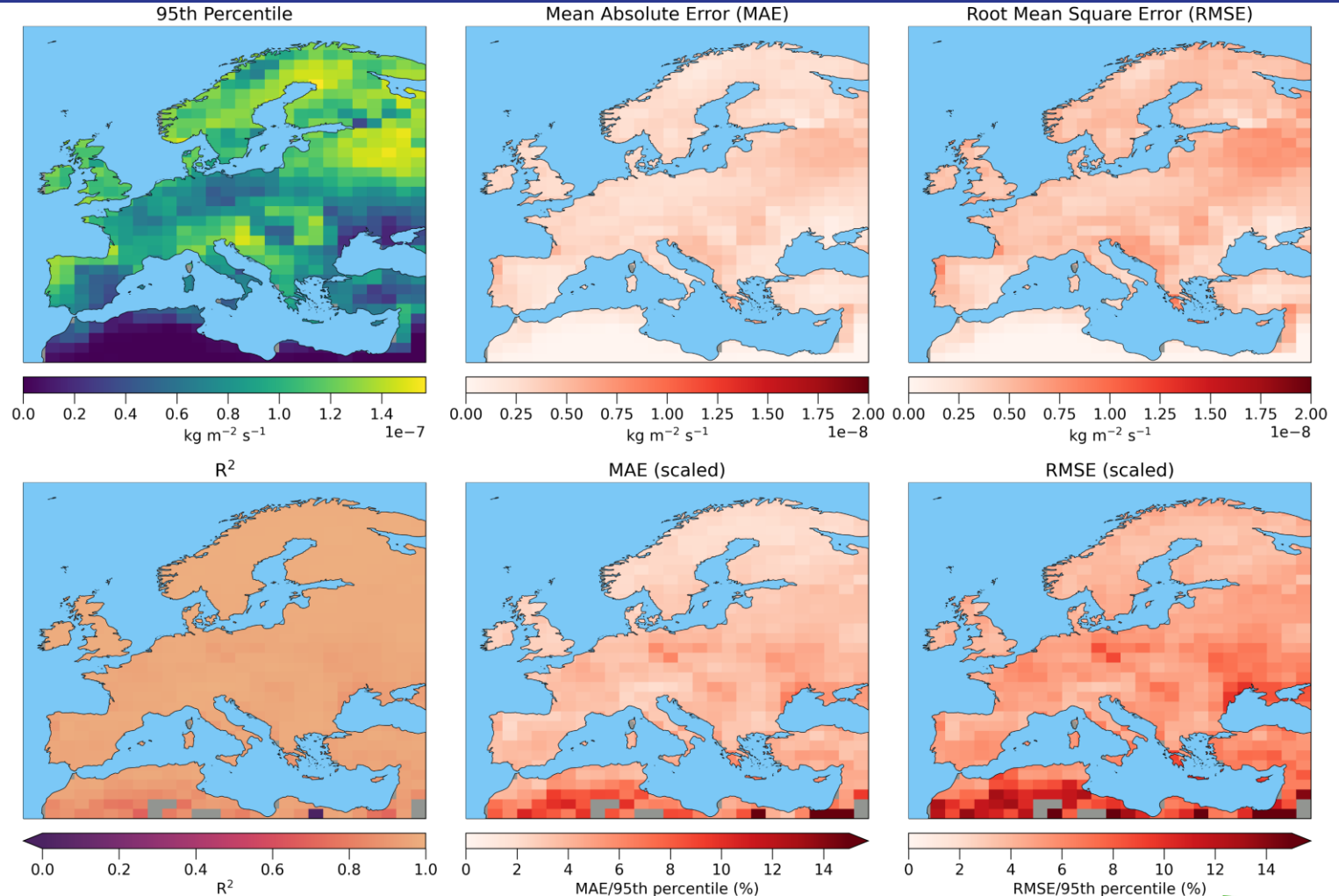
GPP Statistics for Emulator Performance for Validation Period (2020)

INPUTS

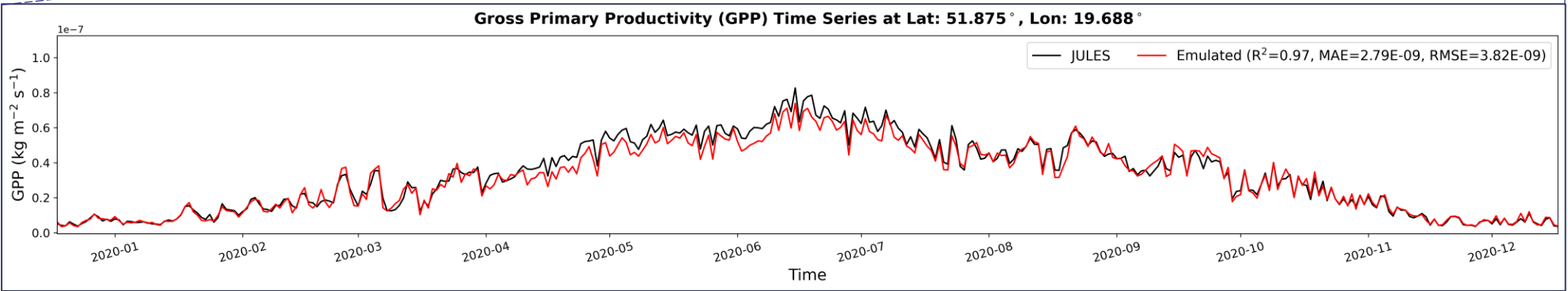
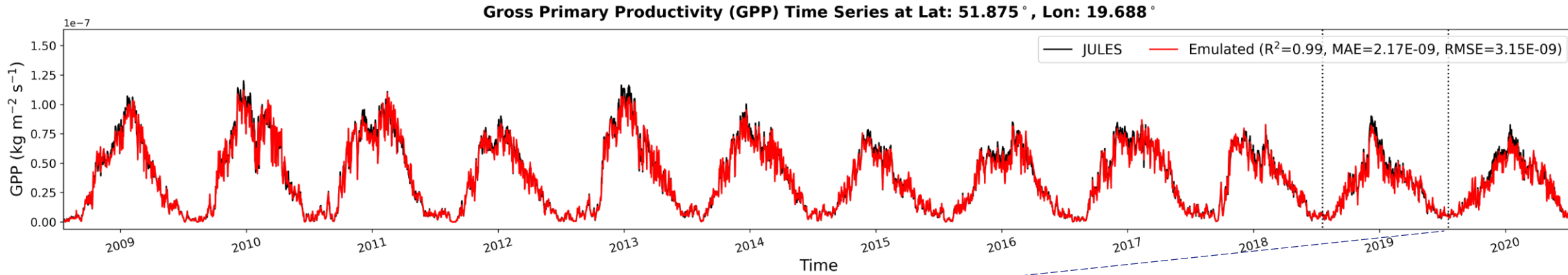
- Min LST
- Max LST
- Soil moisture (top layer)
- FAPAR
- Soil moisture availability factor

OUTPUT

- GPP



Results: Emulating JULES – example time series



INPUTS

- Min LST
- Max LST
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- GPP

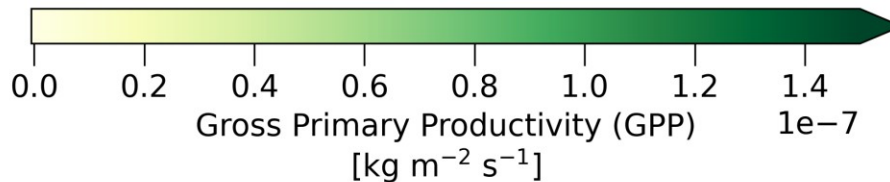
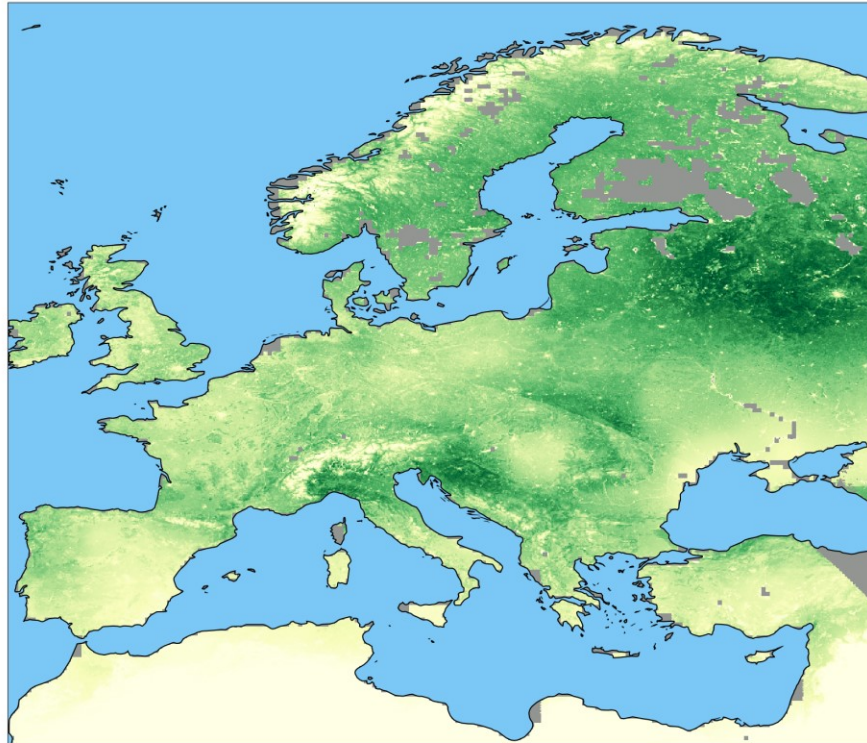
Results: (Emulator + EO) vs JULES – example map

Monthly Average - Emulator vs JULES GPP over Europe on 06-2020

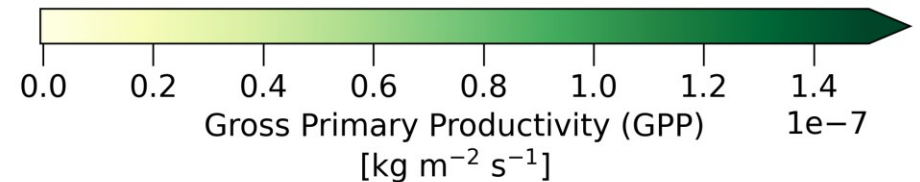
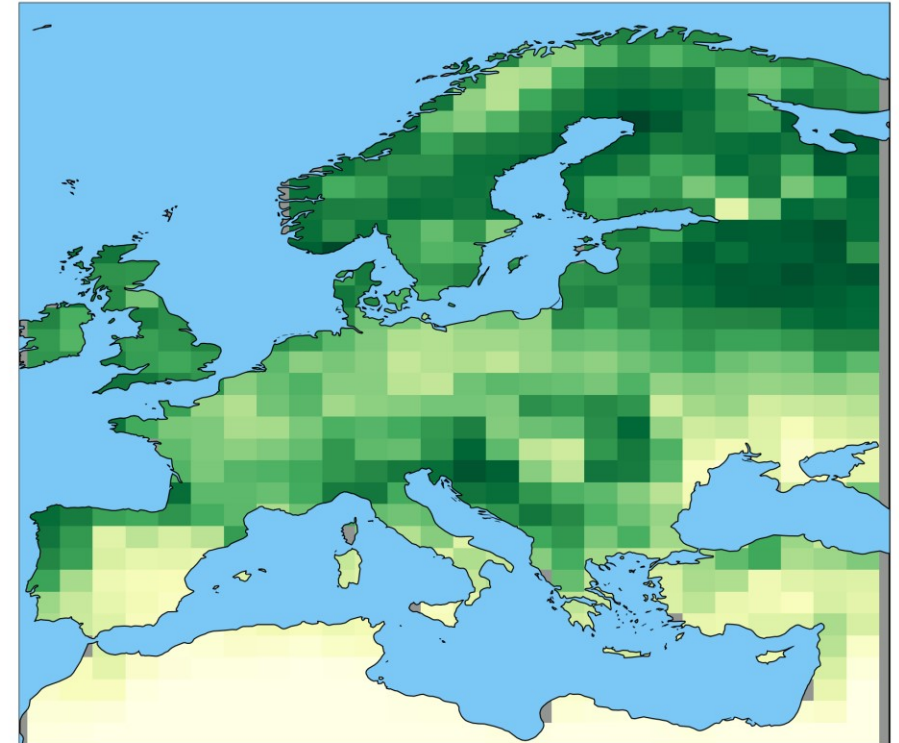
Driving emulator with EO data:

- Constrains physics from JULES with real observations.
- Provides **higher detail** owing to higher resolution of the EO data.

Emulator



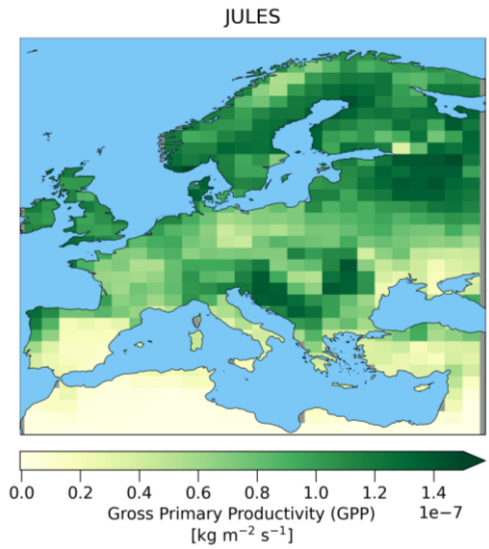
JULES



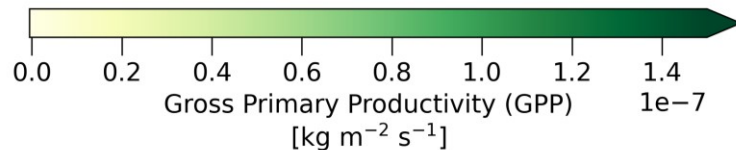
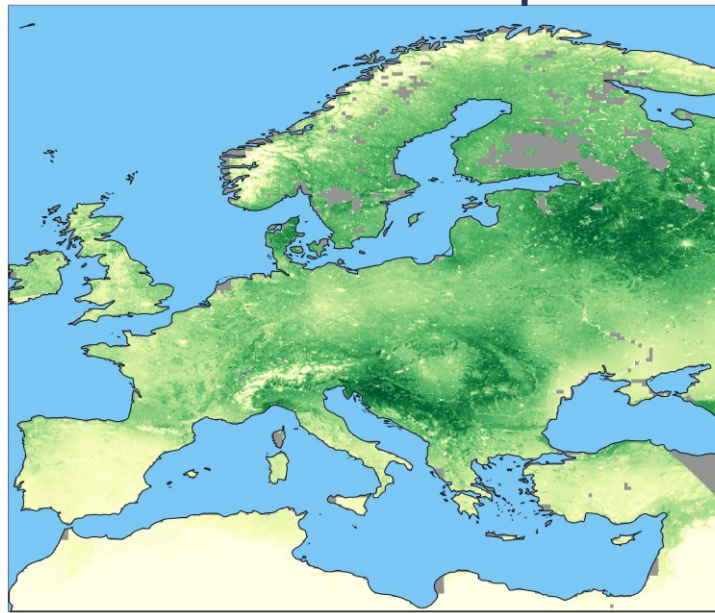
Results: Comparison with other GPP products – example maps

Our data compares well with existing satellite GPP products

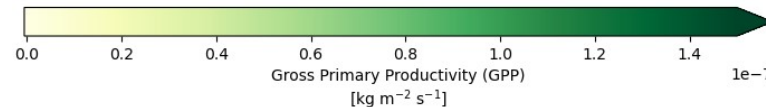
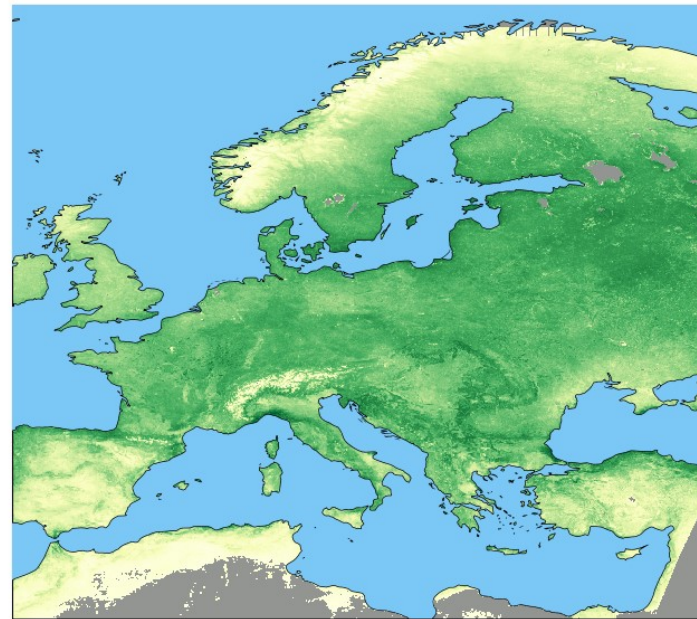
GPP monthly average 06-2019



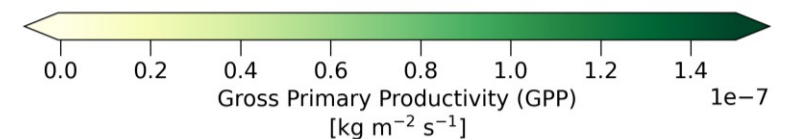
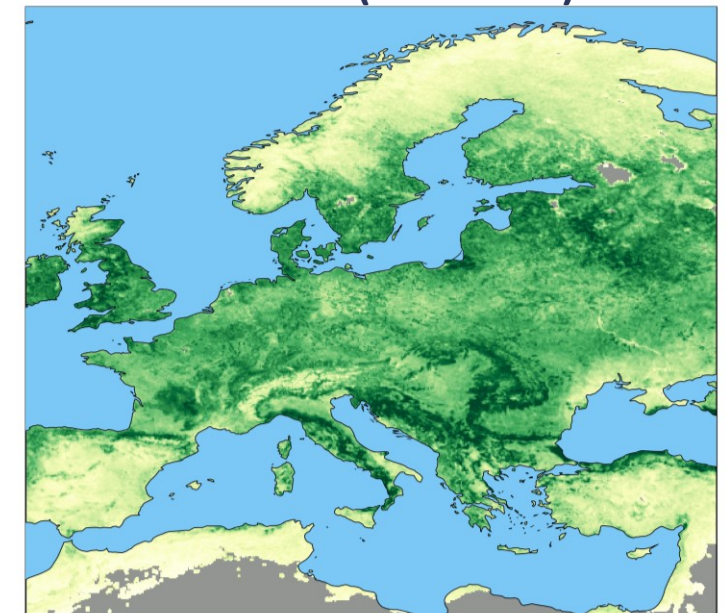
Emulator with EO inputs



MODIS



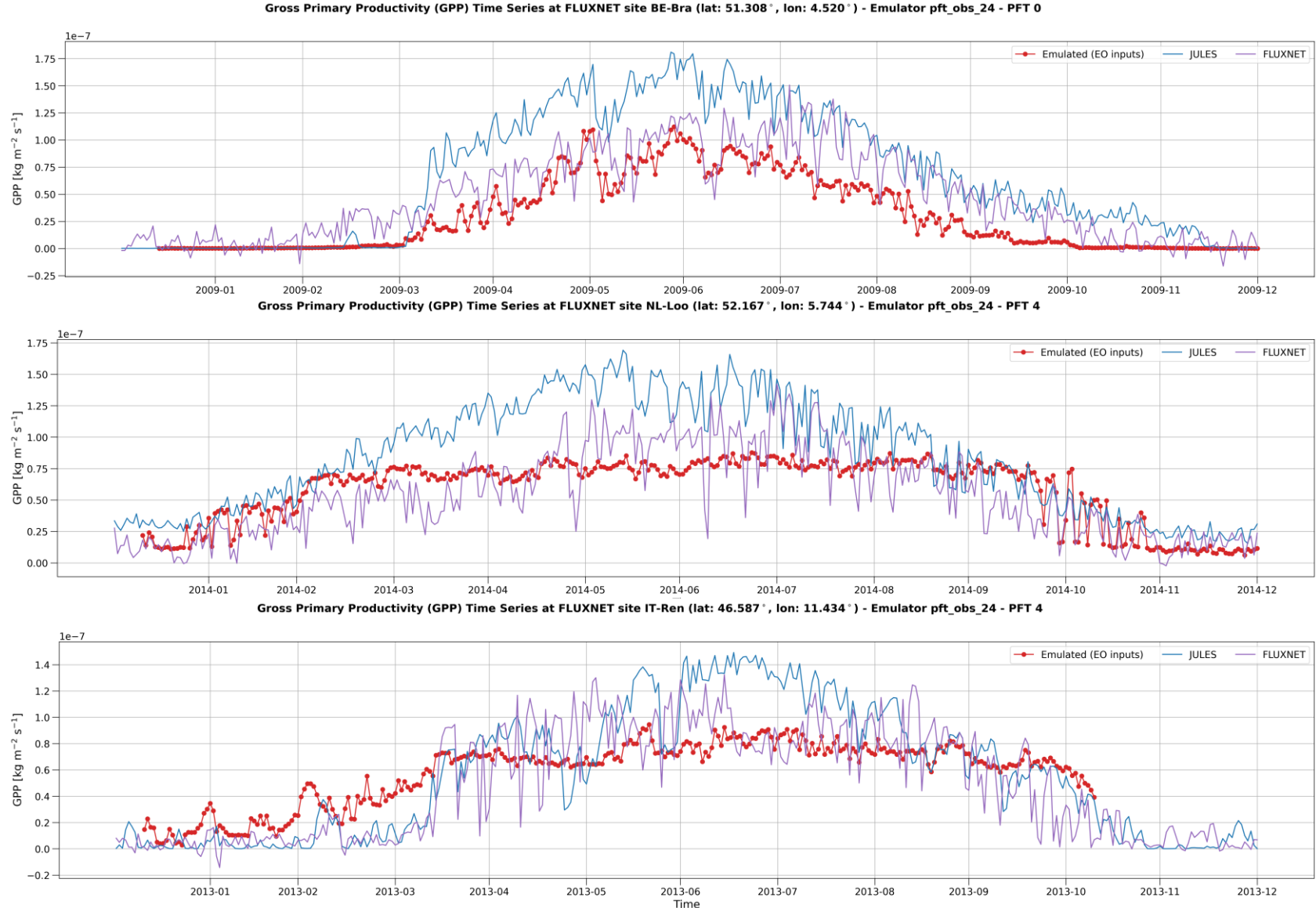
Sen4GPP (SIF-based)



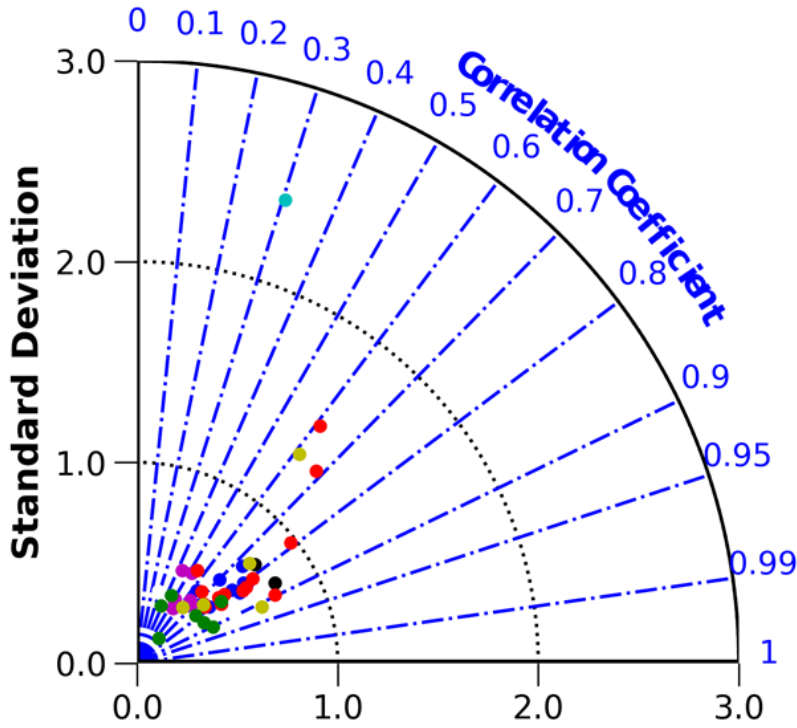
Results: (Emulator + EO) vs JULES vs FLUXNET

Evaluation against FLUXNET

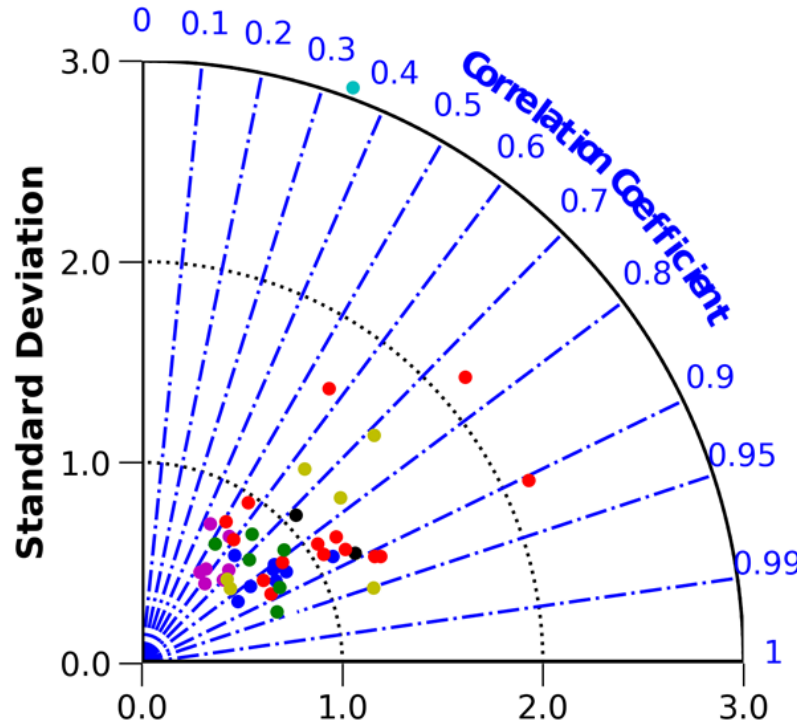
JULES does a good job, though data-driven emulator can do a better job at some sites.



Results: (Emulator + EO) vs JULES vs FLUXNET



a) Emulator

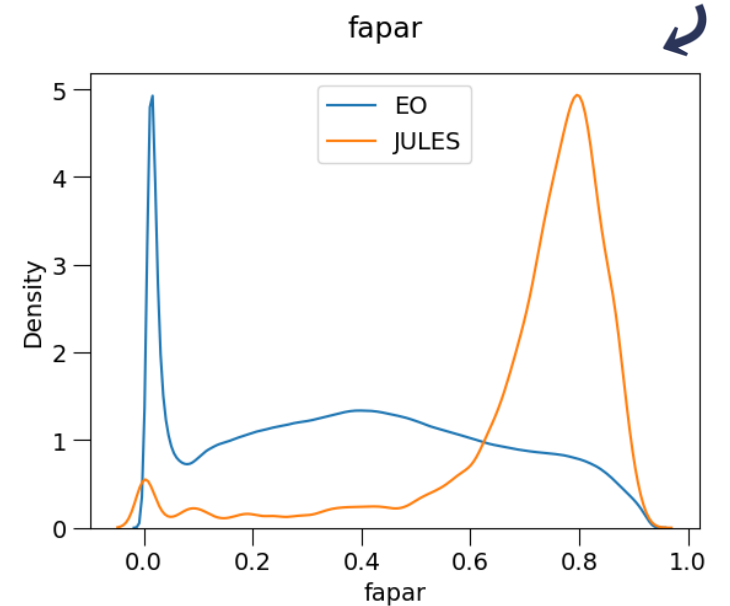


b) JULES

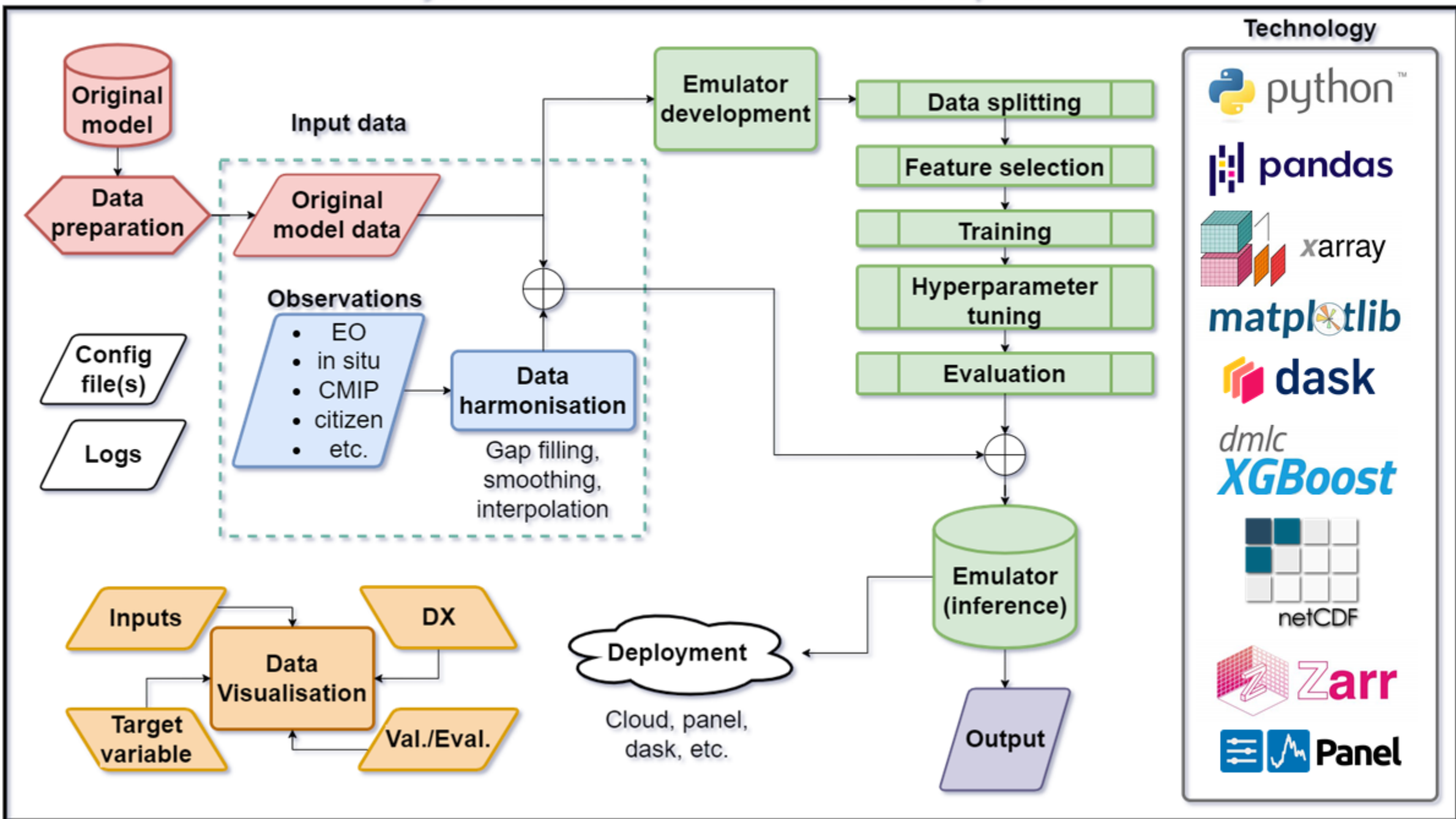
- = evergreen trees, ● = deciduous trees, ● = grasses, ● = crops, ● = mixed forest, ● = open shrubland, ● = other (primarily wetland)

Taylor diagrams reveal that the emulator does not capture the FLUXNET variability well.

EO FAPAR likely to blame.



Python Framework for Emulator Development



Summary

- ❑ **We developed machine-learning emulators of JULES GPP.**
 - ❑ They are very good at emulating JULES.
 - ❑ Information on soil moisture profile was key.
- ❑ **We combined GPP emulators with EO inputs.**
 - ❑ All inputs were observable except fsmc.
 - ❑ Results comparable to MODIS and Sen4GPP, and reasonable agreement with FLUXNET (in some cases better than JULES).
 - ❑ Differences in FAPAR distribution caused reduced variability.

Future Work

- ❑ We are developing a **framework** to speed up development.
- ❑ We are working on a **soil moisture emulator**, which in future will emulate the entire vertical profile.
- ❑ We will further explore the potential of **explainable AI**.

Thank you!

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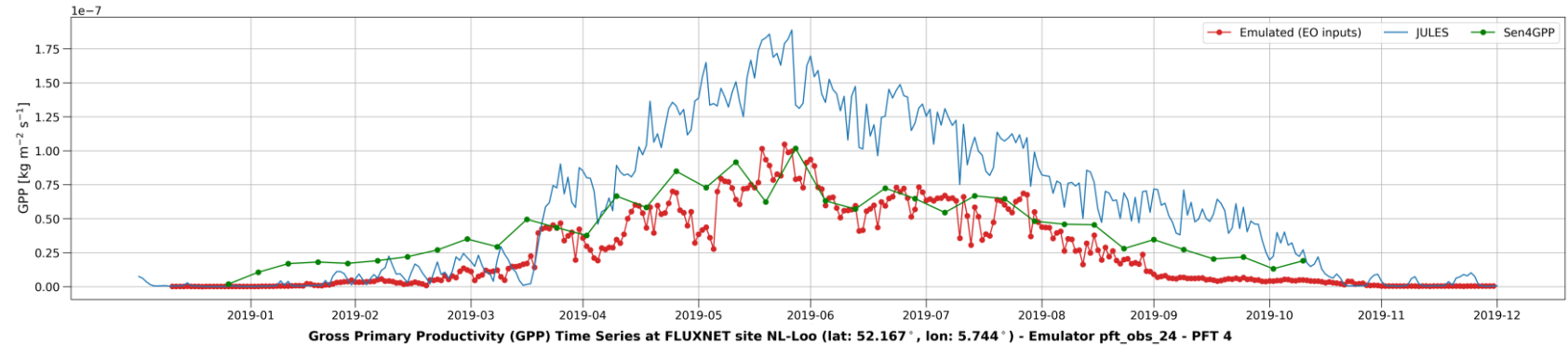


SPARE SLIDES

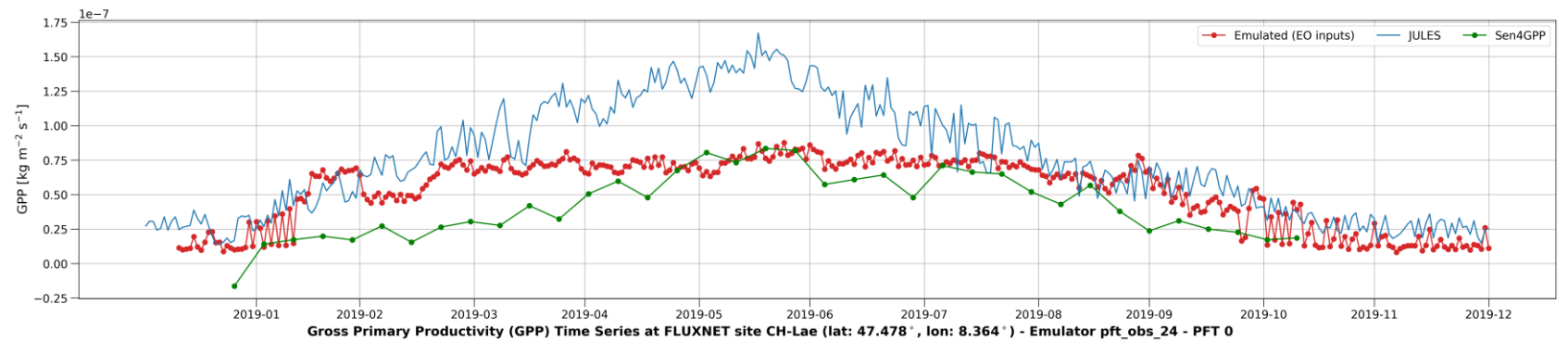
Results: Comparison with other GPP products – example time series

Results at some sites agree well with Sen4GPP.

Gross Primary Productivity (GPP) Time Series at FLUXNET site BE-Bra (lat: 51.308°, lon: 4.520°) - Emulator pft_obs_24 - PFT 0



Gross Primary Productivity (GPP) Time Series at FLUXNET site NL-Loo (lat: 52.167°, lon: 5.744°) - Emulator pft_obs_24 - PFT 4



Gross Primary Productivity (GPP) Time Series at FLUXNET site CH-Lae (lat: 47.478°, lon: 8.364°) - Emulator pft_obs_24 - PFT 0

